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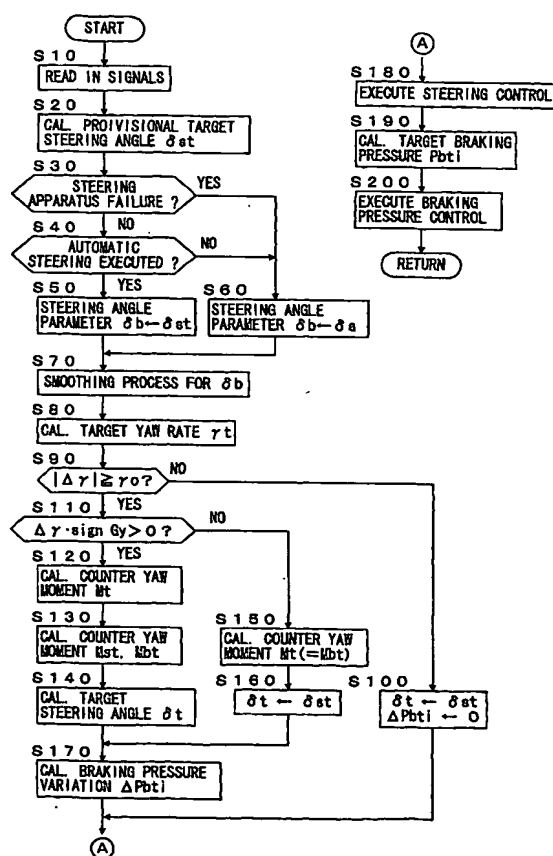
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(54) Title: **VEHICLE STABILITY CONTROL DEVICE**



(57) Abstract: A novel vehicle stability control device through steering wheels independently of the driver's handling operation is provided, in which a suitable steering angle parameter in determining a target value for a turning state parameter is selected. The control device calculates a provisional target steering angle for wheels based upon an amount of an operation of a driver and a predetermined steering characteristic; a target value for the turning state parameter; and a target steering angle for wheels for reducing a magnitude of a deviation of the actual turning state parameter from its target value when the magnitude of the deviation is at a reference value or above, and thereby controlling a steering angle based upon the target steering angle. During execution of controlling the steering angle based upon the target steering angle, the target value of the turning state parameter is calculated based upon the provisional target steering angle.



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